

Series 3 Solutions

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Exercise 1 Elastic equilibrium condition in a two-phase material

We want to demonstrate that the volume average stress in a solid at equilibrium under the condition of zero exterior forces is equal to zero.

$$\int_{\Omega} \sigma_{ij} dV = 0$$

We have the following conditions:

i) $\sigma_{ik} n_k = 0$ where n_k represents the normal to the surface.

ii) $\frac{\partial \sigma_{ik}}{\partial x_k} = 0$: the solid is in equilibrium condition (equation 3.26 of the course)

For the demonstration, we use a small calculation ansatz.

$$\int_{\Omega} \sigma_{ij} dV = \int_{\Omega} \sigma_{ik} \delta_{kj} dV = \int_{\Omega} \sigma_{ik} \frac{\partial x_j}{\partial x_k} dV \quad (1)$$

By integrating by parts, the expression (1) becomes:

$$\int_{\Omega} \sigma_{ik} \frac{\partial x_j}{\partial x_k} dV = \int_{\Sigma} x_j \sigma_{ik} dS_k - \int_{\Omega} x_j \frac{\partial \sigma_{ik}}{\partial x_k} dV = \int_{\Sigma} x_j \sigma_{ik} n_k dS - \int_{\Omega} x_j \frac{\partial \sigma_{ik}}{\partial x_k} dV \quad (2)$$

The surface integral is 0 because of condition i), and the volume integral is also 0 because of the local equilibrium condition ii).

For a two-phase composite material containing a volume Ω_1 of phase 1 and a volume Ω_2 of phase 2, we can write:

$$\int_{\Omega} \sigma_{ij} dV = 0 = \frac{\Omega_1}{\Omega} \int_{\Omega_1} \sigma_{ij} dV + \frac{\Omega_2}{\Omega} \int_{\Omega_2} \sigma_{ij} dV \quad (3)$$

and thus by posing $\frac{1}{\Omega_1} \int_{\Omega_1} \sigma_{ij} dV = \langle \sigma_{ij} \rangle_1$:

$$\Omega_1 \langle \sigma_{ij} \rangle_1 + \Omega_2 \langle \sigma_{ij} \rangle_2 = 0 \quad (4)$$

By dividing (4) by Ω and rewriting in terms of the volume fraction (f) of phase 2, we get:

$$(1-f) \langle \sigma_{ij} \rangle_1 + f \langle \sigma_{ij} \rangle_2 = 0 \quad (5)$$

This formula can be generalized to a multi-phase material made of n phases:

$$\sum_n f_n \langle \sigma_{ij} \rangle_n = 0 \quad (6)$$

Exercise 2 Strain tensor: cylindrical and spherical coordinates

The length of a segment after distortion is given by:

$$d\vec{x}' = d\vec{x} + d\vec{u}$$

Following the equation (3.17) of the course

$$dl'^2 - dl^2 \approx 2d\vec{x}d\vec{u} = 2u_{ik}dx_i dx_k$$

We want to write the tensor u_{jk} in the new basis $(\vec{e}_r, \vec{e}_\theta, \vec{e}_z)$:

$$d\vec{x} = \begin{pmatrix} dx_1 \\ dx_2 \\ dx_3 \end{pmatrix} = dr\vec{e}_r + r d\theta \vec{e}_\theta + dz\vec{e}_z$$

Due to dimension homogeneity, the new variables are:

$$dr, r d\theta, dz$$

$$\vec{u} = u_r \vec{e}_r + u_\theta \vec{e}_\theta + u_z \vec{e}_z$$

$$d\vec{u} = du_r \vec{e}_r + du_\theta \vec{e}_\theta + du_z \vec{e}_z + u_r d\vec{e}_r + u_\theta d\vec{e}_\theta + u_z d\vec{e}_z$$

$$d\vec{e}_r = d\theta \vec{e}_\theta \quad d\vec{e}_\theta = -d\theta \vec{e}_r \quad d\vec{e}_z = 0$$

We differentiate with the new coordinates (like in equation 3.3 of the course):

$$du_r = \frac{\partial u_r}{\partial r} dr + \frac{\partial u_r}{\partial \theta} d\theta + \frac{\partial u_r}{\partial z} dz$$

$$du_\theta = \frac{\partial u_\theta}{\partial r} dr + \frac{\partial u_\theta}{\partial \theta} d\theta + \frac{\partial u_\theta}{\partial z} dz$$

$$du_z = \frac{\partial u_z}{\partial r} dr + \frac{\partial u_z}{\partial \theta} d\theta + \frac{\partial u_z}{\partial z} dz$$

and thus:

$$\begin{aligned}
d\vec{x}d\vec{u} = & \frac{\partial u_r}{\partial r} dr^2 + \left(\frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} \right) r dr d\theta + \frac{\partial u_r}{\partial z} dr dz + \\
& + \frac{\partial u_\theta}{\partial r} r dr d\theta + \left(\frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right) r^2 d\theta^2 + \frac{\partial u_r}{\partial z} r d\theta dz + \\
& + \frac{\partial u_z}{\partial r} dr dz + \frac{1}{r} \frac{\partial u_z}{\partial \theta} r d\theta dz + \frac{\partial u_z}{\partial z} dz^2
\end{aligned}$$

$$\begin{aligned}
u_{rr} &= \frac{\partial u_r}{\partial r} & u_{\theta\theta} &= \left(\frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right) & u_{zz} &= \frac{\partial u_z}{\partial z} \\
2u_{r\theta} &= \left(\frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} + \frac{\partial u_\theta}{\partial r} \right) & 2u_{rz} &= \frac{\partial u_r}{\partial z} + \frac{\partial u_z}{\partial r} & 2u_{\theta z} &= \left(\frac{1}{r} \frac{\partial u_z}{\partial \theta} + \frac{\partial u_\theta}{\partial z} \right)
\end{aligned}$$

Using analogous derivations for spherical coordinates, the new variables are:

$$dr, r d\theta, r \sin \theta d\phi$$

$$\begin{aligned}
u_{rr} &= \frac{\partial u_r}{\partial r} & u_{\theta\theta} &= \left(\frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right) & u_{\phi\phi} &= \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} + \frac{u_r}{r} + \frac{u_\theta}{r(\tan \theta)} \\
2u_{r\theta} &= \left(\frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} + \frac{\partial u_\theta}{\partial r} \right) & 2u_{r\phi} &= \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{\partial u_\phi}{\partial r} - \frac{u_\phi}{r} & 2u_{\theta\phi} &= \frac{1}{r} \left(\frac{\partial u_\phi}{\partial \theta} - \frac{u_\phi}{\tan \theta} + \frac{1}{\sin \theta} \frac{\partial u_r}{\partial \phi} \right)
\end{aligned}$$